# Matrox Imaging Library (MIL) 10 Update 36 Release Notes (milClarityUHD) February 2018

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This document outlines what is new regarding MIL support for the Matrox Clarity UHD and explains the current limitations and particularities.

It also presents last-minute information that did not make it into the manual or on-line help. Note that this help file serves to complement your manual. The information found in this file overrides your formally documented material.

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## 1. MIL Driver for Matrox Clarity UHD

#### 1.1 What's new in MIL 10 Update 36

#### 1.1.1 Summary of new features

The following features are new for this release:

Supports simultaneous acquisition from up to 8 independent input sources. Use MdigAlloc() with M\_DEVn to allocate the digitizer associated with the listed connector, where n is the digitizer device number.

Digitizer device #	Connector name	Description
M_DEV0	Mini-HDMI (type C) connector 0	DVI-D and HDMI 2.0 progressive resolutions up to
M_DEV1	Mini-HDMI (type C) connector 1	2160p60 and interlaced resolutions 1080i50, 1080i59.94 and 1080i60.
M_DEV2	Mini-HDMI (type C) connector 2	DVI-D and HDMI 1.4 progressive resolutions up to 1920 x 1200 p60 and interlaced resolutions 1080i50, 1080i59.94, and 1080i60.
	Analog connector 0	DVI-A progressive resolutions up to 1920 x 1200 p60 and interlaced resolutions (1080i50, 1080i59.94, and 1080i60).
		SD (analog) resolutions for RS170 (720 x 486 i30), CCIR (720 x 576 i25), NTSC (720 x 486 i30), NTSC/YC (720 x 486 i30), PAL (720 x 576 i25), PAL/YC (720 x 576 i25), NTSC RGB (640 x 480 i30), PAL RGB (768 x 576 i25).

M_DEV3	Mini-HDMI (type C) connector 3	Same as M DEV2.
	Analog connector 1	_
M_DEV4	Mini Display Port 1.2 connector 0	Display Port 1.2 progressive resolutions up to 2160p60
M_DEV5	Mini Display Port 1.2 connector 1	and interlaced resolutions 1080i50, 1080i59.94 and 1080i60.
M_DEV6	SDI connector 0	Supports grabbing at up to:
		SD resolutions NTSC (720 x 486 i30) and PAL (720 x 576 i25).
		HD resolutions (720p50, 720p59.94, 720p60, 1080p23.98, 1080p24, 1080p25, 1080p29.97, 1080p30, 1080p50,
M_DEV7	SDI connector 1	1080p50, 1080p59.94, 1080p60, 1080i50, 1080i59.94, 1080i60).
		2K DCI resolutions (2K 23.98p, 2K 24p, 2K 25p).
		UHD resolutions (2160p23.98, 2160p24, 2160p25, 2160p29.97, 2160p30, 2160p50, 2160p59.94, 2160p60).
		4K DCI resolutions (4K 23.98p, 4K 24p, 4K 25p).

- Updated the following MIL hardware-specific examples:
  - MdigCrossBar: This example (accessible from the revised ExampleLauncher or located in .\examples\board-specific\MdigCrossBar) implements a crossbar switch, where any video input can be sent to any video output. This example required a desktop with multiple monitors to view the grabbed images.
  - MultiCameraDisplay: This example demonstrates the acquisition capabilities of Matrox Clarity UHD. Features include:
    - Displaying multiple live streams from multiple boards;
    - No tearing video output;
    - Low latency video output;
    - Live camera addition and removal;
    - Changing the display between windowed and full screen mode;
    - Changing grab buffer pixel formats. Supported pixel formats are: mono8, YUV422 8-bit, YUV422 10-bit (V210), RGB planar, BGR32 8-bit packed, BGR 10-bit packed;
    - Activating image processing on a live stream;
    - Displaying the Feature browser so that the user can control the digitizer and camera settings.

#### 1.1.2 Additions to the command reference

Added support for MbufAlloc1d. Attribute parameter values:

For specifying the intended purpose of the image buffer	
M_DYNAMIC	Specifies an image buffer whose bit-depth and data format are specified by the camera (see M_PFNC_TARGET_FORMAT). To determine the required size of the image buffer, use <b>MdigInquire</b> with <b>M_SIZE_X</b> and <b>M_SIZE_Y</b> , respectively. This value can only be used with <b>M_IMAGE</b> and <b>M_GRAB</b> .
	Please refer to board-specific example MultiCameraDisplay.

- Added support for MdigControl() with M\_GC\_FEATURE\_BROWSER. Unlike with other Matrox products, when using MdigControl() with M\_GC\_FEATURE\_BROWSER, both the digitizer and system controls are displayed in an interactive dialog box.
- Added support for **MsysHookFunction()** with **M\_CAMERA\_PRESENT**. This hooks the function to the presence of the camera.
- Added the following new MbufControl/Inquire() value:

M_YCBCR_RANGE		Specifies whether the YUV buffer's pixel values are encoded in YCbCr. See the MIL documentation for more information.
	M_DEFAULT	Specifies not to encode the YUV buffer's pixel values in YCbCr. This is the default value.
	M_YCBCR_SD	Specifies to encode the YUV buffer's pixel values using the standard-definition YCbCr standard (ITU-R BT.601).
	M_YCBCR_HD	Specifies to encode the YUV buffer's pixel values using the high-definition YCbCr standard (ITU-R BT.709).
	M_YCBCR_UHD	Specifies to encode the YUV buffer's pixel values using the ultra-high-definition YCbCr standard (ITU-R BT.2020). This is new as of MIL 10 Update 36.

Added the following new MdigControl/Inquire() value:

M_PFNC_TARGET_FORMAT		Specifies whether the buffer supports grabbing into 10-bit image buffers in predefined formats, according to the PFNC. Note that this can only be used with a buffer allocated using <b>MbufAlloc1d</b> with an attribute of <b>M_DYNAMIC</b> .
	PFNC_BGRa10p	Specifies to grab at a 10-bit color depth with a BGRa format (B:10,G:10,R:10, A:2).
	PFNC_YCbCr422_10p	Specifies to grab at a 10-bit color depth with a V210 format (YUV422 10-bit).

Added support for grabbing into a native buffer format (allocated using MbufAlloc1d() with M\_DYNAMIC) with MdigGrab() and MdigProcess(), please refer to hardware-specific example MultiCameraDisplay.

### 1.1.3 Known limitations and particularities

- The MIL Driver for Clarity UHD supports the following grab buffer formats:
  - monochrome 8-bit;
  - YUV422 8-bit;
  - YUV422 10-bit (V210) using M DYNAMIC buffers;
  - RGB planar;
  - BGR32 8-bit packed;
  - BGR 10-bit packed using M\_DYNAMIC buffers. This pixel format is not supported when grabbing from a source with a resolution of 3840 x 2160 at 50Hz or higher.
- When grabbing from an SDI source into a monochrome 8-bit or BGR32 packed buffer, the Clarity UHD automatically selects the proper color space equations depending on the input resolution (ITU-R BT.601 for SD, ITU-R BT.709 for HD and ITU-R BT.2020 for UHD). When grabbing into a YUV16 packed buffer the input data is not converted. The color space can be inquired using MbufInquire with M\_YCBCR\_RANGE.
- A maximum of 8 simultaneous grabs from HD sources (1080p60) is supported in YUV16 format.
- A maximum of 2 simultaneous grabs from UHD sources (2160p60) is supported in YUV16 and RGB
  planar formats except when simultaneously grabbing from digitizer device number 0 and 4 or from
  digitizer device 1 and 5. A maximum of 1 live grab from an UHD source is supported in a BGR32 packed
  buffer.
- Supports the RGB 4:4:4 and deep color (10-bit) HDMI colorimetry.
- For the SDI inputs, the following features are not supported:
  - Dual-link;
  - 3D;
  - RGB 4:4:4.

- HDMI inputs are unable to capture from copy-protected HDMI sources (e.g., HDCP).
- Onboard H.264 encoding is not supported.
- Windows' automatic 8.3 file name creation needs to be enabled in order for the MIL installer to access
  the temp folder when the user name contains a space. This option allows Windows to create short
  file/folder name aliases for ones with long names for programs, such as the MIL installer, that don't
  support spaces in the file/folder names. Alternatively, the MIL installer needs to run from a user account
  that belongs to the administrators group and has no spaces in it. Note that the same applies for
  uninstalling MIL.
- The required Visual C++ 2017 Redistributable needs the presence of KB2919442 and KB2919355. These will need to be obtained and applied before restarting this update.
- The MdigCrossbar example may or may not work on Windows 10 depending on the PC's configuration. Please use the new MultiCameraDisplay example.
- MIL/MIL-Lite 10 must NOT be uninstalled if it was installed BEFORE upgrading to the latest version of Windows 10. Failure to do so will corrupt the Windows 10 installation. A fix is coming to remedy the situation.

## 2. Supported operating systems

- 64-bit Windows® 7.
- 64-bit Windows® 10.

## 3. Location of examples (in the help file)

In the MIL online help, the location information written at the top of examples might not be up-to-date. Use MIL Example Launcher to find an example on disk.